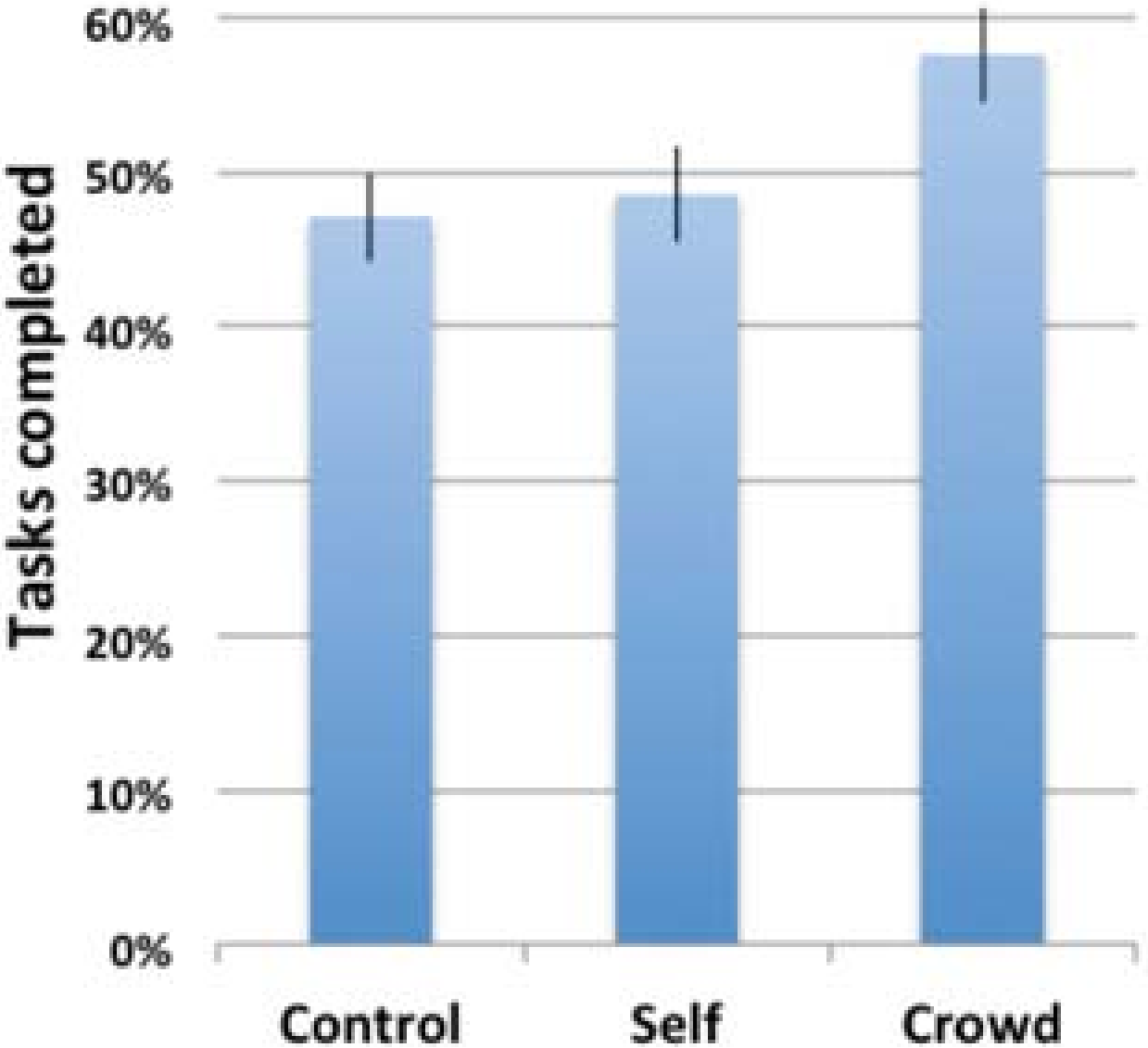

60%
50%
40%
30%
20%
10%
0%
Tasks completed
Control
Self
Crowd